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## Model Checking for Inference

- Seven symbols $P_{1,1}, B_{1,1}, P_{1,2}, P_{2,1}, B_{2,1}, P_{2,2}, P_{3,1}$ have $2^{7}=128$ models. In three of these knowledge base is true.

| $B_{1,1}$ | $B_{2,1}$ | $P_{1,1}$ | $P_{1,2}$ | $P_{2,1}$ | $P_{2,2}$ | $P_{3,1}$ | $R_{1}$ | $R_{2}$ | $R_{3}$ | $R_{4}$ | $R_{5}$ | KB |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| false | false | false | false | false | false | false | true | true | true | true | false | false |
| false | false | false | false | false | false | true | true | true | fcllse | true | false | false |
| $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ |
| false | true | false | false | false | false | false | true | true | false | true | true | false |
| false | true | false | false | false | false | true | true | true | true | true | true | true |
| false | true | false | false | false | true | false | true | true | true | true | true | true |
| false | true | false | false | false | true | true | true | true | true | true | true | true |
| false | true | false | false | true | false | false | true | false | false | true | true | false |
| $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ | $\vdots$ |
| truee | true | true | true | true | true | true | false | true | true | false | true | false |

In all those three $\neg P_{1,2}$ is true, hence there is no pit in [1,2]. On the other hand $P_{2,2}$ is true on two and false in one so it is not confirmed whether there is pit in $[2,2]$ or not.

## Forward Chaining

Determines if a single proposition symbol $q$ is entailed by the knowledge? (data driven reasoning)

- It begins from known facts and adds conclusions of the implication whose all the premises are known
- for $L_{1,1} \wedge$ breeze $\rightarrow B_{1,1}$ if we know $L_{1,1}$ and breeze then $B_{1,1}$ is added in knowledge base ${ }^{1}$

- Applies Modus Ponens

$$
\frac{\phi \quad \phi \rightarrow \psi}{\psi}
$$

- An and-or tree gets constructed


## Recall Wumpus World

- Performance gold +100 , death -100, step -1, arrow -10
- Environment smell around wumpus, breeze around pit
- Actuator turn left/right, forward, grab, release, shoot
- Sensor breeze, glitter, smell, bump, scream


Single Agent, Deterministic, Static, Discrete, !Observable \& !Episodic

- $P_{x, y}$ if there is a pit in $[x, y] \quad$ - $B_{x, y}$ if breeze is in $[x, y]$
- $W_{x, y}$ if wumpus is in $[x, y]$
- $S_{x, y}$ if stench is in $[x, y]$

We know $R_{1}: \neg P_{1,1}, \quad R_{2}: B_{1,1} \Leftrightarrow\left(P_{1,2} \vee P_{2,1}\right)$,
$R_{3}: B_{2,1} \Leftrightarrow\left(P_{1,1} \vee P_{2,2} \vee P_{3,1}\right), \quad R_{4}: \neg B_{1,1}, \quad R_{5}: B_{2,1}$

Validity and Satisfiability

- Validity: sentence is true in all models (tautologies)

$$
\begin{gathered}
A \vee \neg A \\
A \vee B \rightarrow A \vee B
\end{gathered}
$$

- Satisfiability: sentence is true in some models

$$
\begin{gathered}
A \vee \neg B \\
A \rightarrow B
\end{gathered}
$$

Determine whether following sentence is valid or satisfiable

$$
((A \wedge B) \rightarrow C) \leftrightarrow(A \rightarrow(B \rightarrow C))
$$

## Backward Chaining

- Works backward from query
- If query $Q$ is known to be true, then no work is needed.
- Otherwise, find those implications whose conclusion is $Q$
- If all the premises of one of those implications can be proven true (by backward chaining) then $Q$ is true
$P \Rightarrow Q$
- test $(Q)$ is it true ?
$L \wedge M \Rightarrow P$
$B \wedge L \Rightarrow M$
$A \wedge P \Rightarrow L$
$A \wedge B \Rightarrow L$
${ }_{A}^{A}$
B
- test $(L \wedge M)$ ?
- ((test $(A \wedge B)$ or test $(A \wedge P))$ and $\operatorname{test}(B \wedge L)$ ? we know $A$ and $B$ so we have $L$ this gives $M$
- Therefore $P$ and hence $Q$

First Order Logic (Predicate Logic)

- We have constants, variables, predicates and functions
- Here $P(x)$ could means $\forall x$ we have $P(x)$ or $\exists x$ such that $P(x)$
- Variable $x$ has a domain from where it gets values
- $\forall x, \exists y P(x, y)$ is not always same as $\exists y, \forall x P(x, y)$
- When we say $\exists$ a predicate then it is higher order logic


## Examples

(1) Not every customer have purchased milk and bread

$$
\exists c \quad \operatorname{Cust}(c) \wedge[\neg \operatorname{shop}(\text { milk, } c) \vee \neg \operatorname{shop}(\text { bread }, c)]
$$

(2) Only one customer have purchased guitar

$$
\exists x[\operatorname{Cust}(x) \wedge \operatorname{shop}(G, x) \wedge \forall y[\neg(x=y) \wedge \operatorname{Cust}(y) \Rightarrow \neg \operatorname{shop}(G, y)]]
$$

(3) Only one customer have purchased guitar and pen
(9) Highest purchase in forenoon is more than afternoon.

## Inference in First Order Logic

- Universal Elimination $\forall x$ Feels( $x$, king) could be Feels(Raju, king) substitution $\{x /$ Raju $\}$ is done using some ground term.
- Existential Elimination $\exists x$ Feels ( $x$, king) could be Feels(man, king) if man does not appear in knowledge base ${ }^{2}$
- Existential Introduction If Feels(Raju, king) then we can say $\exists x$ Feels(x,king)
(1) It is crime for Magadh to sell formula to a hostile country
(2) Country Bhind, an enemy of Magadh have purchased some formula from Dara
(3) Dara is from Magadh

Question: Is Dara a criminal?

[^0]
## Machine Learning

For some problems we don't precisely know either 1) how to solve, or 2) difficult to specify solution procedure

## Then we go for Machine Learning (ML)

## Computer Science

Artificial Intelligence

http://ktiwari.in/ml

Artificial Intelligence (ZC444) Sun (10:30-12:00PM) online@BITS-Pilani Lecture-13 (Nov 04, 2023) 10/28

## Types of Learning

- Supervised: "right answers" are provided for sufficient training examples. Computer tells "right answers" for new input. Performance measure. (Classification and regression)
- Unsupervised: "right answers" are NOT provided and the computer tries to make sense of the data. How good the spread of items is. (clustering and association rule)
- Semi-supervised: "right answers" are provided for few training examples only
- Active: computer can ask questions. Needs less training. Opposite is passive learning
- Lazy: learner do not consolidate the findings.
- Reinforced: hit and trial method to minimize cost. (game playing)
- Transfer: Learning a task B to do A. (cycle riding for bike riding)
- Deep: processing like human brain


## Applications of ML

In many domains including finance, robotics, bioinformatics, vision, natural language, etc.

- Spam filtering
- Speech/handwriting recognition
- Object detection/recognition
- Weather prediction
- Stock market analysis
- Search engines (e.g, Google)
- Ad placement on websites
- Adaptive website design
- Credit-card fraud detection
- Webpage clustering (e.g.,Google News)
- Machine Translation (e.g., Google Translate)
- Recommendation systems (e.g. Netflix, Amazon)
- Classifying DNA sequences
- Automatic vehicle navigation
- Performance tuning of computer systems
- Predicting good compilation flags for programs
- .. and many more


## Probability of observing a dataset

Assume you are flipping a biased coin where $p(H)=0.4$. What is the probability that you see this dataset $D=<H, H, T, T, H, H>$

- $p(H)=0.4$
- $p(T)=1-p(H)=1-0.4=0.6$
- If all the trails are independent then $p(D \mid \theta)$

$$
\begin{gathered}
=p(H) \times p(H) \times p(T) \times p(T) \times p(H) \times p(H) \\
=0.4^{4} \times 0.6^{2}=0.009216
\end{gathered}
$$

Note: Order of elements in the data set do not matter in the trial. So $p(<H, H, H, H, T, T>)$ is same (in fact any other permutation)

What is $\theta$
It is the parameter. For our case it represents $p(H)=0.4$

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## Bayesian Learning

It is based on assumption that quantities of interest are governed by probability distribution

- Notation
- $P(h)$ : initial probability that hypothesis $h$ holds
- $P(D)$ : probability that data $D$ will be observed
- $P(D \mid h)$ : probability of observing data $D$ given some world in which hypothesis $h$ holds
- $P(h \mid D)$ : probability of holding hypothesis $h$ when data $D$ is observed

$$
P(h \mid D)=\frac{P(D \mid h) P(h)}{P(D)}
$$

The Flow of ML


Hypothesis

| $X$ | $Y$ |
| :---: | :---: |
| 10 | 0 |
| 11 | 0 |
| 12 | 0 |
| 13 | 1 |
| 14 | 0 |
| 15 | 1 |
| 16 | 0 |
| 17 | 1 |
| 18 | 1 |
| 0 | $h_{2}$ |
|  | 1 |
| 0 | $\ldots$ |
| 0 | 0 |
| 1 | $\ldots$ |
| 1 | 0 |
| 1 | 1 |
| 1 | $\ldots$ |
| 1 | 0 |
| 1 | 1 |
| 1 | 0 |
| 1 | $\ldots$ |

- In this example $h_{1}, h_{2}, \ldots$ are hypothesis.
- Hypothesis is a function that aims to provide value of the $Y$
- Can you identify $h_{1}$ and $h_{2}$
- Represent $H$ as candidate set of hypothesis, i.e. $h_{i} \in H$
- Size of $H$ is at least $2^{m}$


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## Maximum a posteriori (MAP)

- Choose a hypothesis that maximizes $P(h \mid D)$

$$
\begin{align*}
h_{\text {MAP }} & =\underset{h \in H}{\operatorname{argmax}} P(h \mid D) \\
& =\underset{h \in H}{\operatorname{argmax}} \frac{P(D \mid h) P(h)}{P(D)} \\
& =\underset{h \in H}{\operatorname{argmax}} P(D \mid h) P(h) \tag{1}
\end{align*}
$$

- Because $P(D)$ is independent of $h$
- If all the hypothesis are equally probable, we may further simplify called maximum likelihood (ML)

$$
\begin{equation*}
h_{M L}=\underset{h \in H}{\operatorname{argmax}} P(D \mid h) \tag{2}
\end{equation*}
$$

For our current example
Let bias for $h_{1}$ and $h_{2}$ be 2/50 and 6/50

| $X$ | $Y$ |
| :---: | :---: |
| 10 | 0 |
| 11 | 0 |
| 12 | 0 |
| 13 | 1 |
| 14 | 0 |
| 15 | 1 |
| 16 | 0 |
| 17 | 1 |
| 18 | 1 | | $h_{1}$ | $h_{2}$ | $\ldots$ |
| :---: | :---: | :---: |
| 0 | 1 | $\ldots$ |
| 0 | 0 | $\ldots$ |
| 0 | 1 | $\ldots$ |
| 1 | 1 | $\ldots$ |
| 1 | 1 | $\ldots$ |
| 1 | 0 | $\cdots$ |
| 1 | 1 | $\cdots$ |
| 1 | 0 | $\cdots$ |
| 1 | 1 | $\cdots$ |

- Since $h_{1}$ and $h_{2}$ are correct with probability $7 / 9$ and $3 / 9$ respectively
- Posterior is $(7 / 9)^{*}(2 / 50)$ and $(3 / 9)^{*}(6 / 50)$
- Normalized probabilities are 0.4375 and 0.5625 respectively
- So MAP hypothesis corresponds to? $h_{2}$
- Can ML hypothesis? it is $h_{1}$
- Brute-force MAP learning algorithm: Evaluates posterior probability for all and returns the one with maximum
- Consistent Learner: learning algorithm is consistent learner if it provides a hypothesis that commits zero error


## Bayes Optimal Classifier

$$
\operatorname{argmax}_{v_{j} \in V} \sum_{h_{i} \in H} P\left(v_{j} \mid h_{i}\right) P\left(h_{i} \mid D\right)
$$

$V=\{\oplus, \ominus\}$

$$
\begin{array}{lll}
P\left(h_{1} \mid D\right)=0.4 & P\left(\ominus \mid h_{1}\right)=0 & P\left(\oplus \mid h_{1}\right)=1 \\
P\left(h_{2} \mid D\right)=0.3 & P\left(\ominus \mid h_{2}\right)=1 & P\left(\oplus \mid h_{2}\right)=0 \\
P\left(h_{3} \mid D\right)=0.3 & P\left(\ominus \mid h_{3}\right)=1 & P\left(\oplus \mid h_{3}\right)=0
\end{array}
$$

Therefore,

$$
\sum_{h_{i} \in H} P\left(\oplus \mid h_{i}\right) P\left(h_{i} \mid D\right)=0.4 \quad \sum_{h_{i} \in H} P\left(\ominus \mid h_{i}\right) P\left(h_{i} \mid D\right)=0.6
$$

and

$$
\operatorname{argmax}_{v_{j} \in\{\oplus, \ominus\}} \sum_{h_{i} \in H} P\left(v_{j} \mid h_{i}\right) P\left(h_{i} \mid D\right)=\ominus
$$

This type of classifier is called a Bayes optimal classifier, or Bayes optimal learner.

## Naive Bayes Classifier

If attribute values are conditionally independent given the target value

- Under this assumption,
- Given a target value, the probability of observing the conjunction $<a_{1}, a_{2}, \ldots, a_{n}>$ is just the product of the probabilities.

$$
P\left(a_{1}, a_{2}, \ldots, a_{n} \mid v_{j}\right)=\Pi_{i} P\left(a_{i} \mid v_{j}\right)
$$

## Naive Bayes classifier

is the one which

$$
\underset{v_{j} \in V}{\operatorname{argmax}} P\left(v_{j}\right) \Pi_{i} P\left(a_{i} \mid v_{j}\right)
$$

## Bayes Optimal Classifier

Switching the question, from "which is most probable hypothesis?" to
"what is the most probable classification of the new instance?"
Is it possible to do better then MAP?
Example: Let posterior probabilities of three hypotheses $h_{1}, h_{2}, h_{3}$
given the training data are $0.4,0.3$, and 0.3 (obviously $h_{1}$ is MAP)

- Let classification of a new instance $x$ is positive by $h_{1}$ and negative by $h_{2}$ and $h_{3}$
- By taking all hypotheses into account, the probability that $x$ is positive is 0.4 , and negative is 0.6
- Most probable classification is negative and it differs from MAP


## Bayes optimal classification:

$$
\underset{v_{j} \in V}{\operatorname{argmax}} \sum_{h_{i} \in H} P\left(v_{j} \mid h_{i}\right) P\left(h_{i} \mid D\right)
$$

where classification $v_{j}$ is from $V$ and $P\left(v_{j} \mid D\right)$ is the correct classification

## Naive Bayes Classifier

Bayes classifier is a highly practical Bayesian learning method

- In some domains, its performance found to be comparable to neural network and decision tree
- The Bayesian approach to classify a new instance is to assign the most probable target value describing the instance $v_{M A P}=\operatorname{argmax}_{v_{j} \in V} P\left(v_{j} \mid a_{1}, a_{2}, \ldots, a_{n}\right)$
- We can use Bayes theorem to rewrite this expression as

$$
\begin{align*}
v_{M A P} & =\underset{v_{j} \in V}{\operatorname{argmax}} \frac{P\left(a_{1}, a_{2}, \ldots, a_{n} \mid v_{j}\right) P\left(v_{j}\right)}{P\left(a_{1}, a_{2}, \ldots, a_{n}\right)} \\
& =\underset{v_{j} \in V}{\operatorname{argmax}} P\left(a_{1}, a_{2}, \ldots, a_{n} \mid v_{j}\right) P\left(v_{j}\right) \tag{3}
\end{align*}
$$

Naive Bayes has assumption is that the attribute values are conditionally independent given the target value

## Example: Naive Bayes Classification

Given the data

| Day | Outlook | Temperature | Humidity | Wind | Play |
| :---: | :---: | :---: | :---: | :---: | :---: |
| D1 | Sunny | Hot | High | Weak | No |
| D2 | Sunny | Hot | High | Strong | No |
| D3 | Overcast | Hot | High | Weak | Yes |
| D4 | Rainy | Mild | High | Weak | Yes |
| D5 | Rainy | Cool | Normal | Weak | Yes |
| D6 | Rainy | Cool | Normal | Strong | No |
| D7 | Overcast | Cool | Normal | Strong | Yes |
| D8 | Sunny | Mild | High | Weak | No |
| D9 | Sunny | Cool | Normal | Weak | Yes |
| D10 | Rainy | Mild | Normal | Weak | Yes |
| D11 | Sunny | Mild | Normal | Strong | Yes |
| D12 | Overcast | Mild | High | Strong | Yes |
| D13 | Overcast | Hot | Normal | Weak | Yes |
| D14 | Rainy | Mild | High | Strong | No |

[^1]Example: Naive Bayes Classification

| Day | Outlook | Temperature | Humidity | Wind | Play |
| :---: | :---: | :---: | :---: | :---: | :---: |
| D1 | Sunny | Hot | High | Weak | No |
| D2 | Sunny | Hot | High | Strong | No |
| D6 | Rainy | Cool | Normal | Strong | No |
| D8 | Sunny | Mild | High | Weak | No |
| D14 | Rainy | Mild | High | Strong | No |



Outlook

$$
\begin{aligned}
& P(\mathrm{Yes})=9 / 14 \\
& P(\mathrm{No})=5 / 14
\end{aligned}
$$

|  | Yes | No |
| :--- | :---: | :---: |
| Sunny | $2 / 9$ | $3 / 5$ |
| Overcast | $4 / 9$ | $0 / 5$ |
| Rainy | $3 / 9$ | $2 / 5$ |

Example: Naive Bayes Classification

For $x=<$ Rainy, Hot, High, Strong $>$

## P(Yes)

- $P(x \mid$ Yes $) \times P($ Yes $)$
- $P($ Rainy $\mid$ Yes $) \times$ $P($ Hot $\mid$ Yes $) \times P($ High $\mid$ Yes $) \times$ $P$ (Strong $\mid$ Yes $) \times P$ (Yes)
- $3 / 9 \times 2 / 9 \times 3 / 9 \times 3 / 9 \times 9 / 14$
- 0.005291...

So the classification of $x$ is No

Example: Naive Bayes Classification

- $P($ Yes $)=9 / 14$
$P(N o)=5 / 14$

Outlook

## Humidity

|  | Yes | No |
| :--- | :--- | :--- |
| High | $3 / 9$ | $4 / 5$ |
| Low | $6 / 9$ | $1 / 5$ |

## Temperature

Wind

|  | Yes | No |
| :--- | :---: | :---: |
| Strong | $3 / 9$ | $3 / 5$ |
| Weak | $6 / 9$ | $2 / 5$ |


|  | Yes | No |
| :--- | :---: | :---: |
| Hot | $2 / 9$ | $2 / 5$ |
| Mild | $4 / 9$ | $2 / 5$ |
| Cool | $3 / 9$ | $1 / 5$ |

Thank You!

Thank you very much for your attention!

## Queries?


[^0]:    ${ }^{2}$ man is a name of person who feels like king
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[^1]:    Determine classification for < Rainy, Hot, High, Strong >

