



CS F425: Deep Learning

08

Neural Network

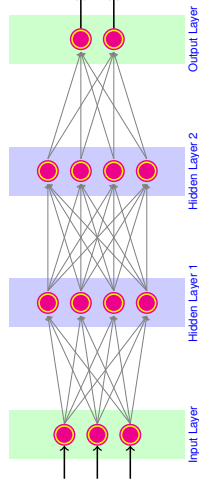


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<http://ktiwari.in/dl>

Neural Network

When neurons are interconnected in layers



- Number of layers may differ
- Nodes in each intermediate layers may also differ
- Multiple output neurons are used for different class
- **Two levels deep** NN can represent any boolean function

Neural Network Applications

NN is appropriate for problems with the following characteristics:

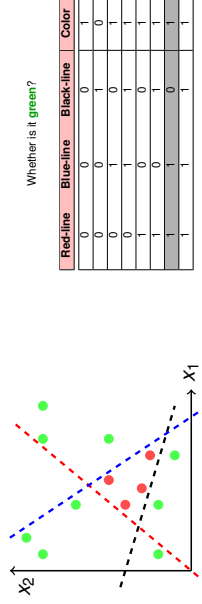
- Instances are provided by many attribute-value pairs (more data)
- The target function output may be discrete-valued, real-valued, or a vector of several real or discrete valued attributes
- The training examples may contain errors
- Long training times are acceptable
- Fast evaluation of the target function may be required
- The ability of humans to understand the learned target function is not important

Brief History

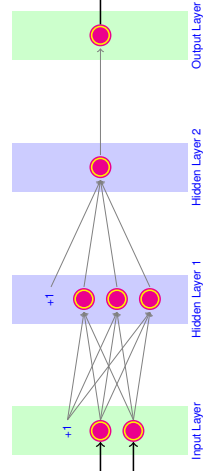
- 1872 Staining/Reticular Theory of Nervous Tissue
- 1943 McCulloch & Pittt (Neuron Model)
- 1947 Donald Hebb (Hebbian Learning)
- 1948 Norbert Cybenetics, optimal filter, feedback)
- 1954 Frank Rosenblatt (Perceptron)
- 1959
- MADALINE Checkers
- 1962 Hubel & Wiesel (Visual Cortex Model)
- 1965 Frank Rosenblatt (MLP: Multi Layer Perceptron)
- 1969 Minsky (Limitations of Perceptron)
- 1986 (Backpropagation)
- 1989 Universal Approximation Theorem
- 1997 LSTM
- 1996 LeCun (ConvNet for MNIST digit)
- 2006 Unsupervised Pre Training
- 2010 Dahl. (Speech Recognition)
- 2012 AlexNet (ImageNet: Computer Vision) 26→16 ... →12% zInat
- 2013 VGG →7.3
- 2014 Google LeNet →6.7
- 2015 ResNet →3.6
- 2017 Densenet
- 2018 Transformers, U-Net segmentation
- 2022 ChatGPT

Waymo, AlphaGo, Yolo
DeepLake, StyleGAN
ChatGPT, AlphaFold

More Example: Design NN for the following data



Whether is it green?



Note: Weights and activation in subsequent layers add power to the model in terms of non linearity.

Perceptron Training (delta rule)

When data is not linearly-separable; error fluctuates with *parameter training* updates. It is difficult to decide, when to stop?

- **Delta rule** converges to a best-fit approximation of the target
- Uses **gradient descent**
- Consider unthresholded perceptron, $\sigma(\vec{x}) = \vec{w} \cdot \vec{x}$
- Training error is defined as

$$E(\vec{w}) = \frac{1}{2} \sum_{d \in D} (t_d - o_d)^2$$

- Gradient would specify direction of steepest increase $\nabla E(\vec{w}) = [\frac{\partial E}{\partial w_0}, \frac{\partial E}{\partial w_1}, \dots, \frac{\partial E}{\partial w_n}]$
- Weights can be learned as $w_i = w_i - \eta \frac{\partial E}{\partial w_i}$
- It can be seen that $\frac{\partial E}{\partial w_i} = \sum_{d \in D} d(t_d - o_d)(-x_{id})$

Perceptron Training (delta rule)

Algorithm 1: Gradient Descent (D, η)

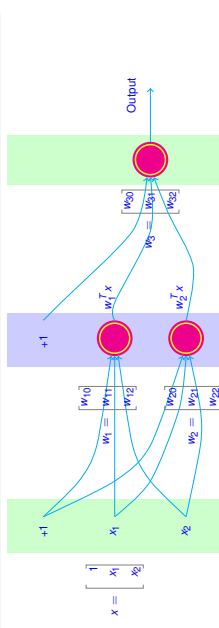
- 1 Initialize w_j with random weights
- 2 repeat
- 3 For each w_i , initialize $\Delta w_i = 0$
- 4 for each training example $d \in D$ do
- 5 Compute output o using model for d whose target is t
- 6 For each w_j , update $\Delta w_j = \Delta w_j + \eta(t - o)X_j$
- 7 For each w_i , set $w_j = w_j + \Delta w_j$
- 8 until **termination condition is met**;
- 9 return w

- A date item $d \in D$, is supposed to be multidimensional $d = (x_1, x_2, \dots, x_n, t)$
- Algorithm converges toward the minimum error hypothesis.
- Linear programming can also be an approach

Thank You!

Linear Activation is Not Much Interesting

NN with perceptrons have limited capability, even with many layers



$$\begin{aligned}
 \text{Output} &= w_{30} \times 1 + w_{31} \times (w_{11}^T x) + w_{32} \times (w_{21}^T x) \\
 &= w_{30} \times 1 + w_{31} \times (w_{10} \times 1 + w_{11} \times x_1 + w_{12} \times x_2) \\
 &\quad + w_{32} \times (w_{20} \times 1 + w_{21} \times x_1 + w_{22} \times x_2) \\
 &= (w_{30} + w_{31}w_{10} + w_{32}w_{20}) + (w_{31}w_{11} + w_{32}w_{21}) \times x_1 \\
 &\quad + (w_{31}w_{12} + w_{32}w_{22}) \times x_2 \\
 &= w_0' + w_1' \times x_1 + w_2' \times x_2
 \end{aligned}$$

Expression of single perceptron

Thank you very much for your attention!