



CS F425: Deep Learning

14 Optimizations For Neural NW



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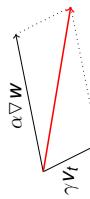
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<http://ktiwari.in/dl>

Momentum Based Gradient Descent 2



- While updating the weights a γ fraction of the previous update is added to the current

$$V_t = \gamma V_{t-1} + \alpha \nabla w_{t-1}$$

α being the learning rate

New weight would be $w_t = w_{t-1} - V_t$

Deep and recurrent neural networks were considered to be almost impossible to train using stochastic gradient descent with momentum. This paper shows that when stochastic gradient descent with momentum uses a well-designed random initialization and a particular type of slowly increasing schedule for the momentum parameter, it can train both DNNs and RNNs

² Ilya Sutskever, Ilya Sutskever et al., "On the importance of initialization and momentum in deep learning," International conference on machine learning, PMLR, 2013.

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AdaGrad

- Uses adaptive learning rate
- Take different step size in different dimensions.
- Velocity
- Update weight using gradient only with different learning weight

$$w_t = w_{t-1} - \frac{\eta}{\sqrt{v_t} + \epsilon} \nabla w$$

Every weight have now different learning rate.

The paper ⁵ presents a new family of subgradient methods that dynamically incorporate knowledge of the geometry of the data observed in earlier iterations to perform more informative gradient-based learning.

⁵ Duchi, John, Elad Hazan, and Yoram Singer. "Adaptive subgradient methods for online learning and stochastic optimization." Journal of machine learning research 12 (2011).

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Training a Neural Network

Least Absolute Deviation (LAD): $\frac{1}{m} \sum_{i=1}^m |o_i - \hat{y}_i|$
Least Square Error (LSE): $\frac{1}{m} \sum_{i=1}^m (o_i - \hat{y}_i)^2$
Cross Entropy Loss (CEL): $-\sum_{i=1}^c o_i \log(\hat{y}_i)$

Training objective is to reduce ERROR

What we can try with multiple epochs?

- Gradient Descent (or batch GD) Cauchy 1847
- Stochastic Gradient Descent Update weights for every example
- Mini-Batch Gradient Descent
- Backpropagation Rumelhart et al 1986¹

¹ Rumelhart, David E., Geoffrey E. Hinton, and Ronald J. Williams. "Learning representations by back-propagating errors." nature 323 (1986): 533-536.

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Nesterov Accelerated Gradient (NAG)

Momentum could overshoot the local minima

- NAG uses look ahead to decide if the learning pace should be slowed to reach local minima to avoid oscillations.
- Pick a future weight

$$w_{t+1} = w_t - \gamma \cdot v_t$$

$$v_t = \gamma \cdot v_{t-1} + \alpha \nabla w_t$$

- Nesterov accelerated gradient ³ is superior to momentum for conventional optimization ⁴

³ Yury Nesterov. A method for unconstrained convex minimization problem with the rate of convergence $O(1/k^2)$. In Doklady AN USSR, volume 269, pp. 545-547, 1983. Sutskever et al. 2013

⁴ Ilya Sutskever, James Martens, George Dahl, and Geoffrey Hinton. On the importance of initialization and momentum in deep learning. In International conference on machine learning, pp. 1139-1147, 2013.

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RMSProp 6

AdaGrad have an issue; v_t becomes large and tend to kill learning rate

- Let us try damped summation
- Moving average

$$E[g^2]_t = \beta E[g^2]_{t-1} + (1 - \beta)(\nabla w)^2$$

β controls how much the current value is significant.

- Update weight using gradient only with different learning weight

$$w_t = w_{t-1} - \frac{\eta}{\sqrt{E[g^2]_t}} \nabla w$$

- RMS is root mean square

⁶ Hinton, G., Srivastava, N., and Swersky, K. Lecture 6d - a separate, adaptive learning rate for each connection. Slides of Lecture Neural Networks for Machine Learning, 2012.

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