

BITS F464: Machine Learning

18

Clustering K-Means



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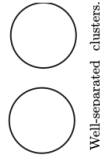
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<http://ktiwari.in/ml>

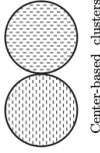
Clustering Approaches



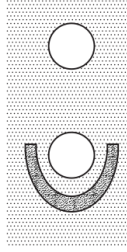
Well-separated clusters.



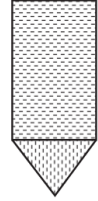
Contiguity-based clusters.



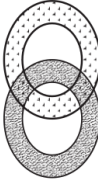
Center-based clusters.



Density-based clusters.



Conceptual clusters.



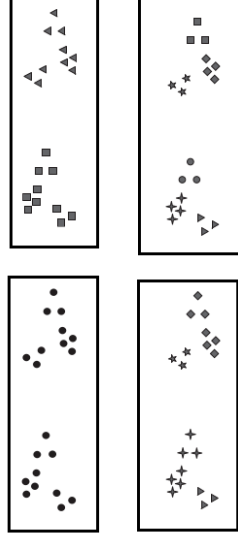
Clustering

- **Unsupervised** in nature (i.e. right answers are not known)
- Clustering is useful to 1) Summarization, 2) Compression, and 3) Efficiently Finding Nearest Neighbors
- **Type:**
 - ▶ Hierarchical (nested) versus Partitional
 - ▶ Exclusive versus Overlapping versus Fuzzy
 - ▶ Complete versus Partial
- **K-means:** This is a prototype-based¹, partitional clustering technique that attempts to find a user-specified number of clusters (K), which are represented by their centroids.

¹object is closer (more similar) to a prototype

Clustering

Grouping data based on their homogeneity (similarity or closeness).



Objects within a group are similar (or related) and are different from the objects in other groups. When it is better?

K-means Algorithm

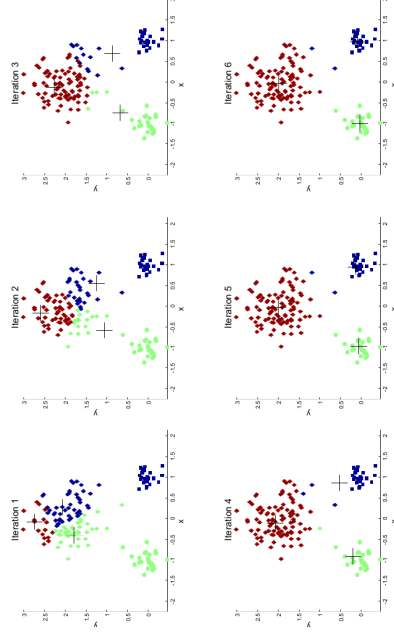
Number of clusters *i.e.* the value of *K* is provided by the user

Algorithm 1: K-means

- 1 Randomly select *K* points as centroids
- 2 **repeat**
- 3 **foreach** datum point *d_i* **do**
- 4 Assign *d_i* to one of the **closest centroids** (thereby forming *K* clusters)
- 5 Recompute centroid (mean) for each cluster
- 6 **until** *The centroids converge;*

Closeness is measured by **Euclidean distance**, cosine similarity, correlation, Bregman divergence *etc*

K-means in Action



Evaluation of K-means²

For a given data set $\{x_1, x_2, \dots, x_n\}$, let K-means partition it in $\{S_1, S_2, \dots, S_K\}$ then the objective is to minimize

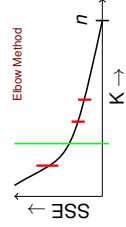
$$\operatorname{argmin}_S \sum_{i=1}^K \sum_{x \in S_i} \operatorname{dist}^2(x, \mu_i)$$

where μ_i corresponds to i^{th} centroid. $\mu_i = \frac{1}{|S_i|} \sum_{x \in S_i} x$

- Typical choice for dist function is Euclidean Distance

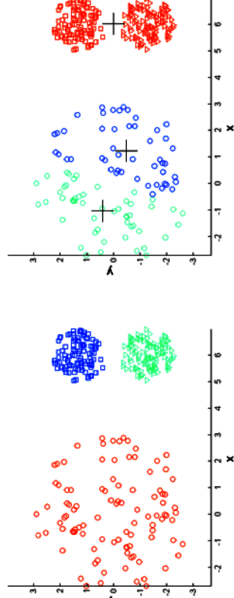
How to proceed?

- Choose a K (How?)
 - ▶ Run K-means algorithm multiple times
 - ▶ Choose clusters corresponding to the one that minimized sum of squared error (SSE)
- If $K = n$, no error.
- Good clustering has smaller K



²Hammerly, Greg and Elkan, Charles, "Learning the k in k-means", pp.281–288, NIPS,2002

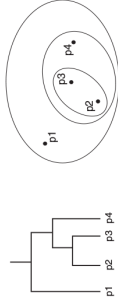
Limitations of K-means



- Has problem when data has
 - ▶ Different size clusters
 - ▶ Different densities
 - ▶ Non-globular shape
- Handling Empty Clusters
- When there are outliers
- Updating Centroids Incrementally

Other Approaches

- **Mini Batch K-Means** less computation and faster convergence
- **K-Medoids**: chooses data point as center and minimizes a sum of pairwise dissimilarities. Resistance to noise and/or outliers
- **Agglomerative Hierarchical Clustering**: repeatedly merging the two closest clusters until a single (Single Link)



- **DBSCAN**: density-based clustering algorithm that produces a partitional clustering, in which the number of clusters is automatically determined by the algorithm.
- **More variations**: Affinity propagation, Mean Shift, Spectral Clustering, Ward hierarchical, Optics, Gaussian Mixture, Birch

Evaluation of K-means

- **Choosing K**: 1) Domain Knowledge, 2) Preprocessing with another algorithm, 3) Iteration on K
- **Initialization of Centers**: 1) Random point in space, 2) Random point of data, 3) look for dense region, 4) Space uniformly in feature space, 5) K-Means++ (high probable if at far)
- **Cluster Quality**: 1) Diameter of cluster verses Inter-cluster distance, 2) Distance between members of a cluster and the cluster center, 3) Diameter of smallest sphere, 4) Ability to discover hidden patterns
- **Efficiently**: mini-batch K-Means

Important Note:

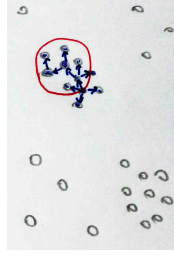
- K-Means and K-NN are different (K nearest neighbors)

K-NN is a **supervised** approach for **classification**

DBSCAN

DBSCAN (Density-Based Spatial Clustering of Applications with Noise) is a spatial clustering algorithm of KDD96

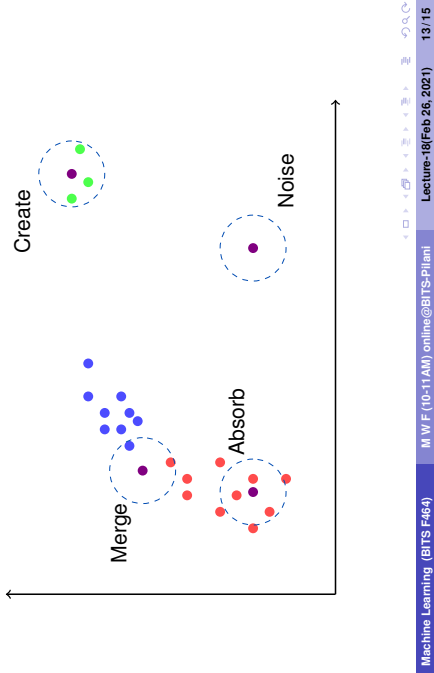
- Parameters (Eps/MinPts) and points (core/border/noise)
- Uses DFS



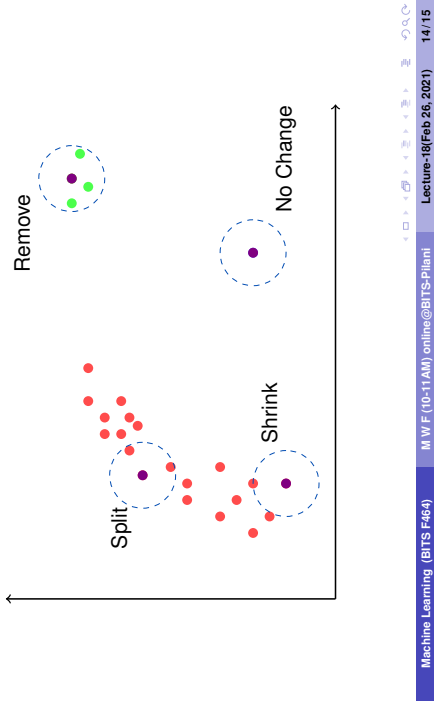
Figures from G. Karppis, E.-H. Han, and V. Kumar, *COMPUTER*, 32(8), 1999

- Disadvantage: Sensitive to parameters
- Advantage: 1) clusters of arbitrary shape, 2) Can handle dynamic databases

Incremental DBSCAN (Addition)



Incremental DBSCAN (Deletion)



Thank You!

Thank you very much for your attention! (Reference³)

Queries ?

³ [1] Book: Machine Learning, ch.9, Tom M. Mitchell. [2] Decision Tree 1: how it works <https://www.coursera.org/learn/machine-learning/lecture/4K05z9P7xv0>. [2] An efficient near-optimal clustering algorithm: Analysis and implementation, T. Kanunop, D. M. Mount, N. Nishiyahu, C. Piatko, R. Silverman, and A. Y. Wu, IEEE Transaction on Pattern Analysis and Machine Intelligence, pp 881–892, 24 (2002) [3] <https://www-users.cs.umn.edu/~kumar/dmbook/ch9.pdf>