

BITS F464: Machine Learning

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Support Vector Machine (SVM)



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<http://ktiwari.in/ml>

Geometry

- Essentially; distance of a point $X = (x_1, x_2, \dots, x_n)$ from a hyperplane represented by $(b, w_1, w_2, \dots, w_n)$ is given by

$$\frac{W^T X + b}{\|W\|}$$

where $\|W\|$ is norm ¹

Classification

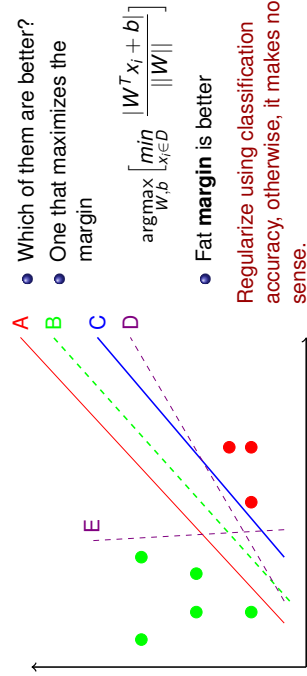
- Hyperplane have two sides (say +ve and -ve)
- which side a point $X = (x_1, x_2, \dots, x_n)$ lies?

Substitute coordinates in the equation $W^T X + b$ and check the sign

¹ $\|W\| = \sqrt{w_1^2 + w_2^2 + \dots + w_n^2}$

Which decision boundary is better

Many decision boundaries with perfect classification are possible



- Which of them are better?
- One that maximizes the margin

$$\operatorname{argmax}_{W,b} \left[\min_{X \in D} \frac{|W^T X_i + b|}{\|W\|} \right]$$

- Fat margin is better

Regularize using classification accuracy, otherwise, it makes no sense.

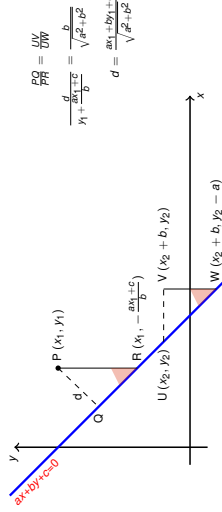
Note: The separating hyperplane would be in middle

Geometry

Determine the length of the perpendicular drawn on a line $ax + by + c = 0$ from a point (x_1, y_1)

$$d = \frac{|ax_1 + by_1 + c|}{\sqrt{a^2 + b^2}}$$

- Proof: (by geometry)



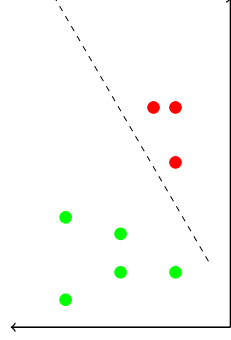
$$\frac{PO}{PQ} = \frac{W}{\|W\|}$$

$$\frac{d}{\sqrt{a^2 + b^2}} = \frac{b}{\sqrt{a^2 + b^2}}$$

$$d = \frac{ax_1 + by_1 + c}{\sqrt{a^2 + b^2}}$$

Special Case of Classification

Consider a linearly separable dataset



- Hyperplane is defined by W
- Margin is the distance of nearest data point from the separating hyperplane

$$\min_{X \in D} \frac{|W^T x_i + b|}{\|W\|}$$

- Most of the real-world problems are NOT linearly separable
- Sometime data could be transformed to a high-dimensional space where classes may be linearly separable
- Caution: this could lead to over-fitting

Look Closer

$$\operatorname{argmax}_{W,b} \left[\min_{X \in D} \frac{|W^T x_i + b|}{\|W\|} \right] = \operatorname{argmax}_{W,b} \frac{1}{\|W\|} \left[\min_{X \in D} |W^T x_i + b| \right] = \operatorname{argmax}_{W,b} \frac{1}{\|W\|}$$

- Hypothesis is a hyperplane represented by W ; scaled parameter $k.W$ also represents the same hyperplane
- For the points on hyperplane $W^T x_i + b = 0$
- For points NOT on hyperplane $W^T x_i + b = 0$ changes if $k.W$ is used instead of W . Ultimately different $\min_{X \in D} |W^T x_i + b|$
- You can get any value for $\min_{X \in D} |W^T x_i + b|$ by changing the value of k without changing the hyperplane

So without loss of generality, let us fix $\min_{X \in D} |W^T x_i + b| = 1$

Support Vector Machine (SVM)

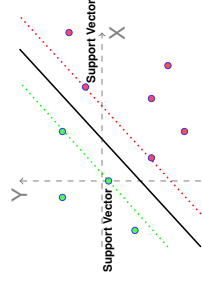
SVM is a linear decision machine; uses $\text{sign}(w^T x^{(i)} + b)$ for decision

- We want $w^T x^{(i)} + b \geq \gamma$ for +ve (and $< -\gamma$ for -ve)
- Distance of a point (x, y) from hyper plane $w^T x + b = 0$ is $\frac{|w^T x + b|}{\|w\|}$
- Distance can be maximized, by either **maximizing b** or by **minimizing $\|w\|$**

- We need $w^T x + b \geq \gamma \|w\|$
let $\gamma \|w\| = 1$

- ▶ $w^T x + b \geq 1$ if x is +1
- ▶ $w^T x + b \leq -1$ if x is -1

- It leads to $y^{(i)}(w^T x^{(i)} + b) \geq 1$
- Points with $y^{(i)}(w^T x^{(i)} + b) = 1$ are called **support vector**



Support Vector Machine (SVM)

- Minimization of w is same as minimization of $\phi(w) = \frac{1}{2} w \cdot w$
- Other constraints are $y^{(i)}(w^T x^{(i)} + b) \geq 1$
- However, for support vectors $y^{(i)}(w^T x^{(i)} + b) = 1$
- Define a Lagrangian Multiplier to optimize $L(w, b) = \frac{1}{2} w \cdot w - \sum \alpha_i y^{(i)}(w^T x^{(i)} + b) - 1$
- Derivative $\frac{\partial L}{\partial b} = - \sum \alpha_i y^{(i)}$ that should be equated to zero

$$\sum_{i=1}^m \alpha_i y^{(i)} = 0$$

- Derivative $\frac{\partial L}{\partial w} = w - \sum \alpha_i y^{(i)} x^{(i)}$ equated to zero gives

$$w = \sum_{i=1}^m \alpha_i y^{(i)} x^{(i)}$$

Lagrangian with optimized values

$$L(w, b) = \frac{1}{2} w \cdot w - \sum \alpha_i (y^{(i)}(w x^{(i)} + b) - 1)$$

$$L(w, b) = \frac{1}{2} w \cdot w - \sum \alpha_i y^{(i)} w x^{(i)} - \sum \alpha_i y^{(i)} b + \sum \alpha_i$$

$$L(w, b) = \frac{1}{2} w \cdot w - \sum \alpha_i y^{(i)} w x^{(i)} + \sum \alpha_i$$

$$L(w, b) = \frac{1}{2} \sum \alpha_i y^{(i)} y^{(j)} x^{(i)} x^{(j)} - \sum \alpha_i \alpha_j y^{(i)} y^{(j)} x^{(i)} x^{(j)} + \sum \alpha_i$$

$$L(w, b) = \sum \alpha_i - \frac{1}{2} \sum \alpha_i \alpha_j y^{(i)} y^{(j)} x^{(i)} x^{(j)}$$

- One have to maximize $L(w, b)$ subject to $\alpha_i \geq 0$ and $\sum_{i=1}^m \alpha_i y^{(i)} = 0$

- If α_i is large the corresponding training sample is support vector. Otherwise, when $\alpha_i = 0$ it is not a support vector
- Optimized α_i provides the value of $w = \sum_{i=1}^m \alpha_i y^{(i)} x^{(i)}$ to be used in linear decision boundary

Support Vector Machine (SVM)

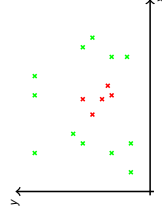
Advantages

- It works well with clear margin of separation
- Do not stuck to local minima
- Effective in high dimensional spaces
- It is effective in cases where number of dimensions is greater than the number of samples
- Memory efficient as it uses a subset of training points in decision (called support vectors)

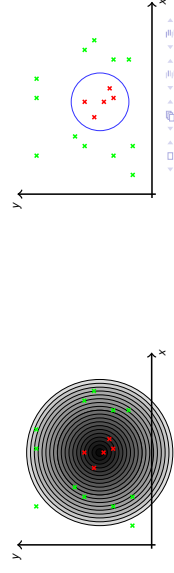
Disadvantages

- It doesn't perform well, when data set is large as the training time is higher
- Doesn't perform well when target classes are overlapping
- Probability estimates are not directly provide
- Higher classification confidence for points lying far from the decision boundary

Transformation: An Example



- Transform all 2D points $(x^{(i)}, y^{(i)})$ in 3D as $(x^{(i)}, y^{(i)}, z)$ where $z = (x^{(i)} - x_c)^2 + (y^{(i)} - y_c)^2$



Thank You!

Thank you very much for your attention!

Queries ?

(Reference²)

² [1] Text Book: Machine Learning, by Tom M.Mitchel [2] Mod-01 Lec-29 Support Vector Machine <https://www.youtube.com/watch?v=SRFsvrRH5QTE>